










Operating instructions

	Home
	General information
	Safety instructions
	Technical data
	Mechanical installation
	Electrical installation
	Commissioning
	Troubleshooting
	Disposal



i550 protec frequency inverter

0.37 ... 75 kW

General information

Overview

Information

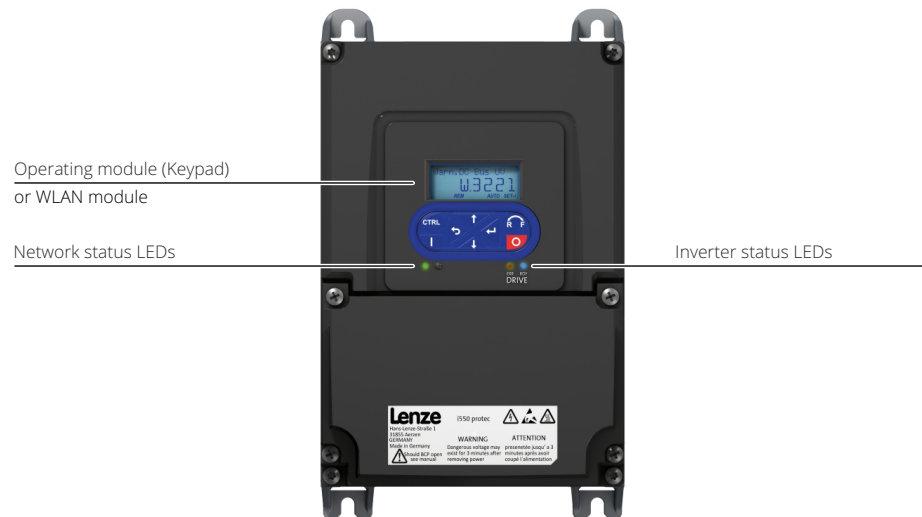
Identification

Extension box

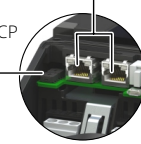
Conventions



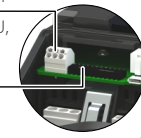
Hardware overview of the inverter



X2xx Network, Option
EtherCAT, PROFINET,
EtherNet/IP, Modbus TCP
Rotary encoder switch



X2xx Network, Option
CANopen, Modbus RTU,
IO-Link
DIP switch



X16 Diagnostic interface

Shield connection
Control cable

X100 Power supply

PE connection

Cable glands
with shield connection for motor cable

X20 Memory module

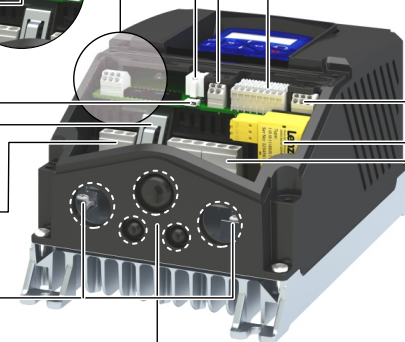
X109 PTC input

X3 Control terminals
Standard I/O

X9 Relay output

X1 Safety module
Slot

X105 Motor connection
Brake resistor
connection
DC bus



General information

Overview

Information

Identification

Extension box

Conventions



Please read this documentation carefully before installing the inverter and observe the safety instructions!

This document only includes the most frequently asked questions and presents them in a simplified form for a better overview. Detailed technical and functional explanations can be found in the comprehensive product documentation. The complete documentation, further information and tools regarding Lenze products can be found on the Internet:

www.Lenze.com

Application as directed

- The product is a piece of professional equipment intended for use by trades, specific professions or industry, and not for sale to the general public. IEC 60050 [IEV161-05-05]
- To prevent personal injury and damage to property, higher-level safety and protection systems must be used!
- All transport locks must be removed.
- The product may only be operated under the specified operating conditions and in the specified mounting positions.
- The product is only suitable for installation in control cabinets and, depending on the protection class, for wall mounting.
- The product must only be actuated with motors that are suitable for the operation with inverters.
- The product must not be operated in private areas, in potentially explosive atmospheres and in areas with harmful gases, oils, acids and radiation.

Device-specific standards and directives

- The product meets the protection requirements of the Low-Voltage Directive 2014/35/EU.
- The harmonized standard EN IEC 61800-5-1 is used for the inverters. (Europe).
- UL 61800-5-1 and CAN/CSA C22.2 No.274 are the North American electrical safety standards.

Relevant standards and directives for the operator

- If the product is used in accordance with the technical data, the drive systems comply with the EN IEC 61800-3 categories (Category C2 is similar to FCC Class A).
- The test voltage for insulation resistance tests between a control potential of 24 V and PE must be measured in accordance with EN IEC 61800-5-1.
- The cables must be installed in accordance with EN IEC 60204-1 or US National Electrical Code NFPA 70/Canadian Electrical Code C22.1.

Commissioning

- Commissioning or starting the operation as directed of a machine with the product is prohibited until it has been ensured that the machine meets the regulations of the Machinery Directive 2006/42/EG and the standard EN IEC 60204-1.
- Commissioning or starting the operation as directed is only permissible if the EMC Directive 2014/30/EU is complied with.
- In residential areas, the product may cause EMC interference. The operator is responsible for executing the interference suppression measures.

Licence information PROFINET

The PROFINET firmware is optional. The PROFINET firmware uses the following open source software packages under a modified GPL license: eCos Operating System. These components are used at the operating system level of the firmware. The protocol stack does not use source code under a GPL license.

View license: <http://ecos.sourceware.org/license-overview.html>

General information

Overview

Information

Identification

Extension box

Conventions



Identification of the products

I

5

5

A

P

137¹

F²

0³

A⁴

7⁵

0⁶

0⁷

K⁸

00S⁹

1

Rated power	
	[kW]
137	0.37
155	0.55
175	0.75
211	1.1
215	1.5
222	2.2
230	3
240	4
255	5.5
275	7.5
311	11
315	15
318	18.5
322	22
330	30
337	37
345	45
355	55
375	75

2

Mains voltage and connection type	
A	1/N/PE AC 120 V
B	1/N/PE AC 230/240 V
C	3/PE AC 230/240 V
D	1/N/PE AC 230/240 V 3/PE AC 230/240 V
F	3/PE AC 400 V 3/PE AC 480 V
G	3/PE AC 480 V 3/PE AC 600 V

3

Product variant	
0	Standard device
1	Empty extension box
2	Extension box and disconnect switch

4

Integrated functional safety	
0	Without safety function
A	Basic Safety - STO

5

Degree of protection	
3	IP31, uncoated / NEMA 1
7	IP66, uncoated / NEMA 4X
8	IP55, uncoated / NEMA 12

6

Interference suppression	
0	Without
1	Integrated RFI filter

7

Application area	
0	Default parameter setting: Region EU (50-Hz networks)
1	Default parameter setting: Region US (60-Hz networks)

8

Product extension	
0	Standard I/O
K	Keypad with Standard-I/O
W	WLAN module with Standard I/O

9

Network	
00S	Without
02S	CANopen
03S	Modbus RTU
06S	IO-Link
xKS	EtherCAT
xLS	PROFINET
xMS	EtherNet/IP
xWS	Modbus TCP

General information

Overview

Information

Identification

Extension box

Conventions



Extension box

The i550 protec frequency inverter 0.37 ... 22 kW can be ordered with an IP66 housing (extension box) enlarged at the bottom. This extension box can be purchased empty or with an integrated disconnect switch. It offers additional space or holes for cable entries.

Additional solution options for the extension box in the "empty" model:

- Integration of terminals for looping through the mains voltage
- Integration of control elements
- Integration of a brake rectifier for controlling a 180 V / 205 V DC holding brake



General information

Overview

Information

Identification

Extension box

Conventions



Safety instructions

By safety instructions, we mean information for the use of products that serves to warn the user of hazards and to instruct behavior that will not result in harm to people. In this document, these are distinguished as follows according to ANSI Z535.6:

DANGER!

Indicates an extremely hazardous situation. Failure to comply with this instruction will result in severe irreparable injury and even death.

WARNING!

Indicates an extremely hazardous situation. Failure to comply with this instruction may result in severe irreparable injury and even death.

CAUTION!

Indicates a hazardous situation. Failure to comply with this instruction may result in slight to medium injury.

NOTE

Indicates a material hazard. Failure to comply with this instruction may result in material damage.

Numeric notation

As a rule, a period is used as a decimal separator in this documentation.

Example: 1234.56

Safety instructions

Basic safety instructions

Residual hazards



Basic safety instructions

DANGER!

Disregarding the following basic safety instructions and safety information may lead to severe personal injury and damage to property!

- Only use the product as directed.
- Never commission the product in the event of visible damage.
- Never modify the product technically.
- Never commission the product before assembly has been completed.
- Never operate the product without the required covers.
- Connect/disconnect all pluggable connections only in deenergized condition!
- Only remove the product from the installation in the deenergized state.
- The product can - depending on their degree of protection - have live, movable or rotating parts during or after operation. Surfaces can be hot. Surfaces can be hot.
- Observe all specifications of the corresponding documentation supplied. This is the condition for safe and trouble-free operation and the achievement of the specified product features.
- The procedural notes and circuit details given in the associated documentation are suggestions and their transferability to the respective application must be checked. The manufacturer of the product does not take responsibility for the suitability of the process and circuit proposals.
- All work with and on the product may only be carried out by qualified personnel. IEC 60364 and CENELEC HD 384 define the qualifications of these persons:
 - They are familiar with installing, mounting, commissioning, and operating the product.
 - They have the corresponding qualifications for their work.
 - They know and can apply all regulations for the prevention of accidents, directives, and laws applicable at the place of use.

WARNING!

Functional safety

Certain variants of the product support safety functions (e.g. "Safe torque off (STO)") in accordance with the requirements of 2006/42/EC: Machinery Directive [UKCA: S.I. 2008/1597 - The Supply of Machinery (Safety) Regulations 2008]. Be sure to observe the instructions in the documentation regarding the integrated safety technology.

NOTE

Device protection

Carry out insulation resistance tests between 24-V control potential terminals and PE. The maximum test voltage must not exceed 110 V DC.

NOTE

Foreseeable misuse

Inverters are not to be operated with DC motors.

Safety instructions

Basic safety instructions

Residual hazards



Residual hazards

The user must take the residual hazards mentioned into consideration in the risk assessment for his/her machine/system. If the above is disregarded, this may result in injuries to persons and material damage!



DANGER!



Dangerous electrical voltage

During operation and up to 20 minutes after power-off, hazardous electrical voltages may be present at the connections of the product.

The leakage current against earth (PE) is > 3.5 mA AC or > 10 mA DC.



Possible consequences

- Death or serious injury from electric shock



Protective measures

- Any work on the product must only be carried out in a deenergized state.
- Check that no voltage is present!
- After switching off the mains voltage, observe the signs on the product.
- After switching off, wait until the drive is at a standstill.
- Implement the measures required by EN IEC 61800-5-1 or EN IEC 60204-1, i.e. fixed installation and standards-compliant PE connection.



Degree of protection - Protection of persons and device protection

Information applies to the mounted and ready-for-use state.

Motor protection

With some settings of the inverter, the connected motor can be overheated.

- E.g. via the operation of self-ventilated motors at low speeds over a long period.
- E.g. by operating DC-injection braking over a long period.

Product

Observe the warning signs on the product!



Dangerous electrical voltage

Before working on the product, check whether all power connections are deenergized!

After mains disconnection, the power terminals carry the hazardous electrical voltage for the time specified next to the symbol!



Electrostatic sensitive devices

Before working on the product, the staff must ensure to be free of electrostatic charge.



High leakage current

Carry out fixed installation and PE connection in compliance with the following standard:

EN IEC 61800-5-1/EN IEC 60204-1



Hot surface

Use personal protective equipment or wait until the device has cooled down!


Protection of the machine/system

- Drives can reach dangerous overspeeds, e.g. from setting high output frequencies for motors and machines which are not suitable. The inverters do not provide any protection against such operating conditions. Use additional external components for this purpose.
- Only switch the contactor in the motor cable when the inverter is inhibited. Switching them when the inverter is enabled is only permissible when no monitoring components respond.

Motor

In the event of a short circuit of two power transistors, a residual movement of up to 180°/number of pole pairs on the motor may occur (e.g. 4-pole motor): Residual movement max. $180^\circ/2 = 90^\circ$.

Technical data

		Standards and operating conditions		
Approvals for the market		CE (European Union)		Further information and certificates of approval: https://www.lenze.com/en-de/products/inverters/frequency-inverters/i550-protec-frequency-inverter/
		UKCA (Great Britain)		
		UL (USA)		
		CSA (Canada)		
		CCC (China)		
		EAC (Belarus, Russia, Kyrgyzstan, Kazakhstan and Armenia)		
UkSepro (Ukraine)				
Environment		RoHS		
Energy efficiency	High Efficiency	EN IEC 61800-9-2	Class IE2	
Degree of protection	EN	EN IEC 60529	IP31 IP55 IP66	Data applies for operationally ready mounted state and not in wire range of terminals
	NEMA	NEMA 250	Type 1 Type 12 Type 4X outdoor	
	EI	UL 50	Type 1	
		UL 50E	Type 4X outdoor	
Climate	Operation	EN 60721-3-3:1995 + A2:1997	3K3 (-30 ... +60 °C)	Operation at a switching frequency of 2 or 4 kHz: Above +45°C: reduce rated output current by 2.5 %/°C
				Operation at a switching frequency of 8, 12 or 16 kHz: Above +40°C: reduce rated output current by 2.5 %/°C
			3C2 3C3 (for IP66)	For chemically active substances
			3S2 3S3 (for IP66)	For mechanically active substances
Power systems		TT, TN		Voltage to earth: max. 300 V
Mains switching		3 x within one minute possible		
Max. motor cable length		Device-specific; see technical data in project planning document		
Max. output frequency		0 Hz ... 599 Hz		
Overload capacity		Heavy Duty: 200 % for 3s, 150 % for 60s Light Duty 167 % for 3 s, 125 % for 60 s (only applies to devices with protection class IP31/NEMA 1)		
Further standards and operating conditions can be found in the project planning documents.				

Mechanical installation

Without extension box

With extension box

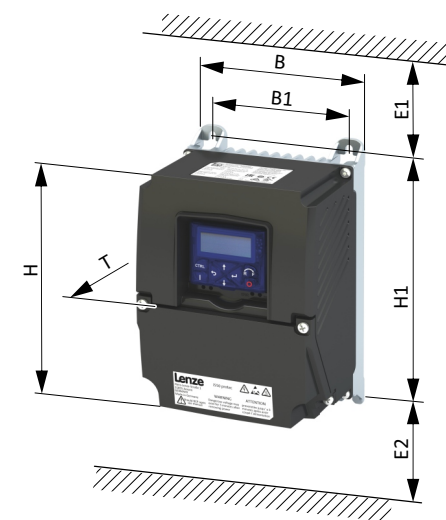


Dimensions and assembly – Inverters without extension box

NOTE

The specified installation clearances are minimum dimensions to ensure a sufficient air circulation for cooling purposes. They do not take into account the bending radii of the connecting cables.

Inverter	Rated power	Weight	H	B	T	H1	B1	Screws	E1	E2
	[kW]								[kg]	[mm]
1-phase mains connection 120 V devices										
I55APxxxA	0.37	1.8	190	140	117	205	115	4x M5	>50	>50
I55APxxxA	0.75 ... 1.1	2.7	205	140	140	220	115	4x M5	>50	>50
1-phase mains connection 230/240 V devices										
I55APxxxB	0.37 ... 0.75	1.8	190	140	117	205	115	4x M5	>50	>50
I55APxxxB	1.1 ... 2.2	2.7	205	140	140	220	115	4x M5	>50	>50
1-/3-phase mains connection 230/240 V devices										
I55APxxxD	0.37 ... 0.75	1.7	190	140	117	205	115	4x M5	>50	>50
I55APxxxD	1.1 ... 2.2	2.6	205	140	140	220	115	4x M5	>50	>50
I55APxxxC	3 ... 5.5	4.8	250	180	168	267	150	4x M5	>50	>50
I55APxxxC	7.5 ... 11	5	290	180	173	310	150	4x M5	>50	>50
I55APxxxC	15 ... 18.5	9.4	405	230	187	428	200	4x M6	>50	>100
I55APxxxC	30	46	778	298	285.5	810	225	4x M8	>100	>130
I55APxxxC	45	53	778	298	377.5	810	225	4x M10	>100	>260
3-phase mains connection 400/480 V devices										
I55APxxxF	0.37 ... 0.75	1.8	190	140	117	205	115	4x M5	>50	>50
I55APxxxF	1.1 ... 2.2	2.7	205	140	140	220	115	4x M5	>50	>50
I55APxxxF	3 ... 5.5	4.9	250	180	168	267	150	4x M5	>50	>50
I55APxxxF	7.5 ... 11	5.1	290	180	173	310	150	4x M5	>50	>50
I55APxxxF	15 ... 22	10.2	405	230	187	428	200	4x M6	>50	>100
I55APxxxF	30 ... 45	46	778	298	285.5	810	225	4x M8	>100	>130
I55APxxxF	55 ... 75	53	778	298	377.5	810	225	4x M10	>100	>260
3-phase mains connection 600 V devices										
I55APxxxG	0.75	1.8	190	140	117	205	115	4x M5	>50	>50
I55APxxxG	1.5 ... 2.2	2.7	205	140	140	220	115	4x M5	>50	>50
I55APxxxG	3 ... 5.5	4.9	250	180	168	267	150	4x M5	>50	>50
I55APxxxG	7.5 ... 11	5.1	290	180	173	310	150	4x M5	>50	>50
I55APxxxG	15 ... 22	10.2	405	230	187	428	200	4x M6	>50	>100



Mechanical installation

Without extension box

With extension box



Dimensions and assembly – Inverters with extension box

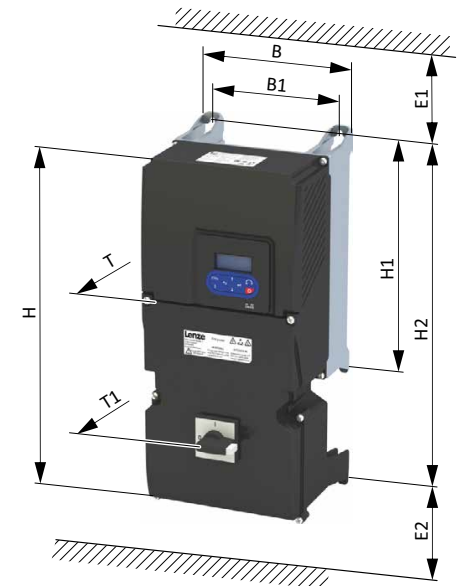
NOTE

The specified installation clearances are minimum dimensions to ensure a sufficient air circulation for cooling purposes. They do not take into account the bending radii of the connecting cables.

Inverter	Rated power	Weight	H	B	T	T1	H1	H2	B1	Screws	E1	E2
	[kW]											
1-phase mains connection 120 V devices												
I55APxxxA	0.37	2.3 / 2.5	330	140	117	151	205	337	115	6x M5	>50	>50
I55APxxxA	0.75 ... 1.1	3.3 / 3.5	346	140	140	173	220	352	115	6x M5	>50	>50
1-phase mains connection 230/240 V devices												
I55APxxxB	0.37 ... 0.75	2.3 / 2.5	330	140	117	151	205	337	115	6x M5	>50	>50
I55APxxxB	1.1 ... 2.2	3.3 / 3.5	346	140	140	173	220	352	115	6x M5	>50	>50
1-/3-phase mains connection 230/240 V devices												
I55APxxxD	0.37 ... 0.75	2.2 / 2.4	330	140	117	151	205	337	115	6x M5	>50	>50
I55APxxxD	1.1 ... 2.2	3.2 / 3.4	346	140	140	173	220	352	115	6x M5	>50	>50
I55APxxxC	3 ... 5.5	5.7 / 5.9	396	180	165	199	267	403	150	6x M5	>50	>50
I55APxxxC	7.5 ... 11	6 / 6.2	471	180	170	203.5	310	479.5	150	6x M5	>50	>50
I55APxxxC	15 ... 18.5	11.4 / 11.9	612	230	184	220	428	620	200	6x M6	>50	>100
3-phase mains connection 400/480 V devices												
I55APxxxF	0.37 ... 0.75	2.3 / 2.5	330	140	117	151	205	337	115	6x M5	>50	>50
I55APxxxF	1.1 ... 2.2	3.3 / 3.5	346	140	140	173	220	352	115	6x M5	>50	>50
I55APxxxF	3 ... 5.5	5.8 / 6	396	180	165	199	267	403	150	6x M5	>50	>50
I55APxxxF	7.5 ... 11	6.1 / 6.3	471	180	170	203.5	310	479.5	150	6x M5	>50	>50
I55APxxxF	15 ... 22	11.5 / 12	612	230	184	220	428	620	200	6x M6	>50	>100
3-phase mains connection 600 V devices												
I55APxxxG	0.75	2.3 / 2.5	330	140	117	151	205	337	115	6x M5	>50	>50
I55APxxxG	1.5 ... 2.2	3.3 / 3.5	346	140	140	173	220	352	115	6x M5	>50	>50
I55APxxxG	3 ... 5.5	5.8 / 6	396	180	165	199	267	403	150	6x M5	>50	>50
I55APxxxG	7.5 ... 11	6.1 / 6.3	471	180	170	203.5	310	479.5	150	6x M5	>50	>50
I55APxxxG	15 ... 22	11.5 / 12	612	230	184	220	428	620	200	6x M6	>50	>100

Please observe the following:

- The lower weight applies for the i550 protec with empty extension box, and the higher weight applies for the i550 protec with extension box and disconnect switch.
- The dimension T1 is only relevant for i550 protec with disconnect switch.



Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



Preparation

For wiring, the housing cover must be removed:

1. Loosen the 4 screws in the housing cover using a crosstip screwdriver.
2. Remove housing cover



After completing the electrical installation, replace the housing cover using the 4 screws to maintain the degree of protection.

NOTE

Assembly does not satisfy protection class requirements

Possible consequences: Damage to property due to ingress of humidity and foreign bodies.

- All cable glands and mounting parts must at least correspond to the protection class of the inverter.
- All openings in the housing must be closed according to the protection class.
- The cover must be screwed on with the specified tightening torque.
- Always use cable glands with long thread.

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			

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Cable gland with shield connection

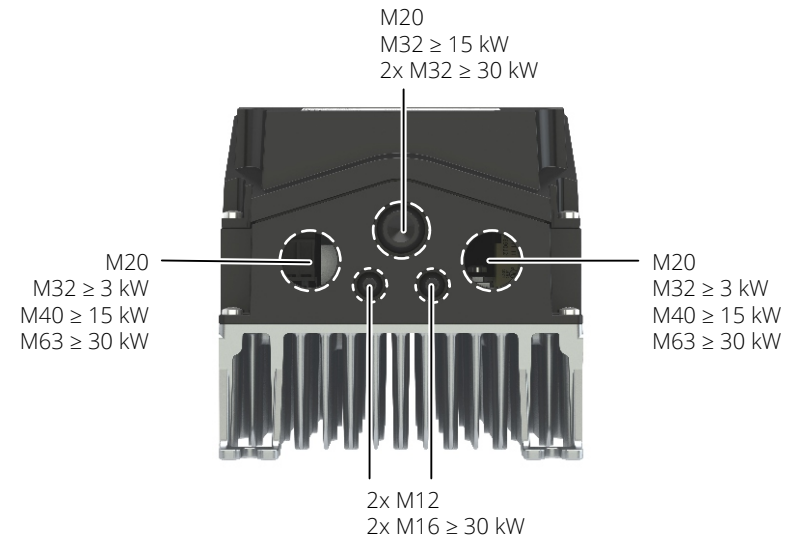
Thanks to its protection class, the inverter can be installed directly on the wall. For connection, the device has cable glands on the bottom. Suitable mounting sets with screwed connections are available as accessories (see project planning document).

Rated power	kW	0.37 ... 2.2	3 ... 11	15 ... 22	30 ... 75
With pre-drilled holes:					
Mains cable		M20 / ½" Conduit hub	M32 / 1" Conduit hub	M40 / 1¼" Conduit hub	M63 / 2" Conduit hub
Motor cable		M20 / ½" Conduit hub	M32 / 1" Conduit hub	M40 / 1¼" Conduit hub	M63 / 2" Conduit hub
Additional positions with centering aid:					
Control cables, network cables, brake resistor		2x M12 1x M20 / ½" conduit hub 2x M20 / ½" conduit hub *	2x M12 1x M20 / ½" conduit hub 2x M20 / ½" conduit hub *	2x M12 1x M32 / 1" conduit hub 2x M20 / ½" conduit hub *	2x M16 2x M32 / 1" conduit hub

* Only for extension box

When using electrically conductive conduits:

- Individual unshielded conductors or multi-core unshielded cables which have been laid in a metallic conduit are considered equivalent for the purposes of EMC conformity of a shielded motor cable.
- Both a rigid and a flexible metallic conduit are permissible.
- The conduit must be connected properly at both ends using metallic screwed connections on the inverter and on the motor so as to connect all devices.
- Non-metallic junctions or screwed connections which interrupt the electrical conductivity of the metallic conduit are not permissible.



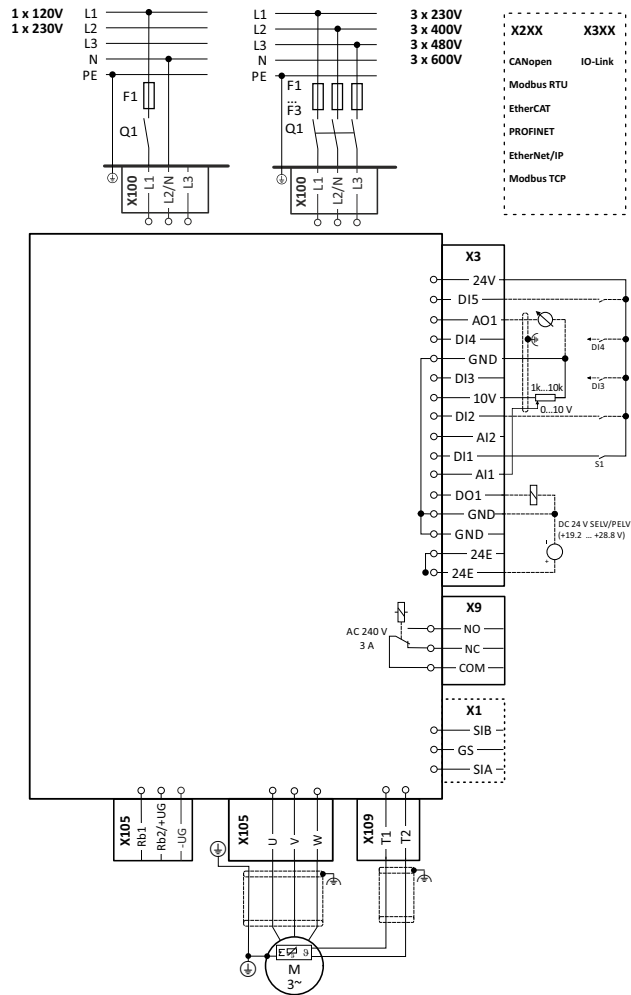
Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



Connection diagram

The connection diagram is considered exemplary for all voltage and power classes.

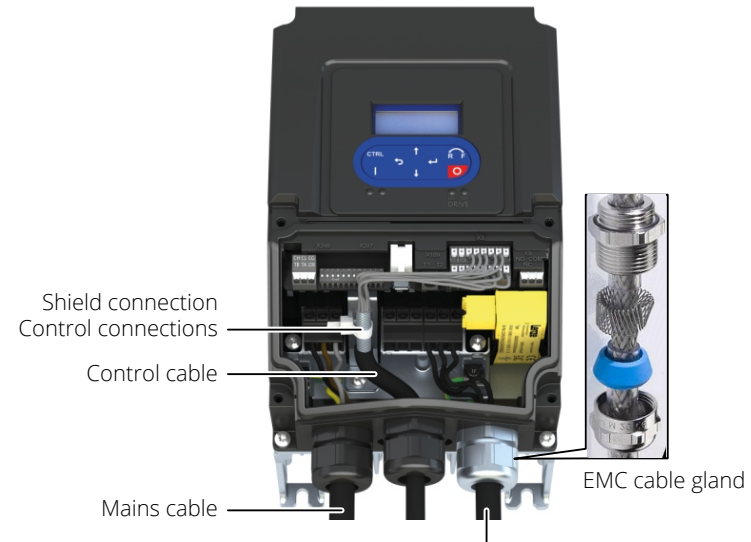


EMC-compliant installation

The drive system of inverter and drive comply with the EMC Directive 2014/30/EU if they are installed according to the specifications of CE-typical drive systems. These guidelines should also be followed in installations requiring FCC Part 15 or ICES 001 compliance. The structure at the installation location must support the EMC-compliant installation with shielded motor cables.

- Please use sufficiently conductive shield connections.
- Connect the housing with shielding effect to the grounded mounting plate with a surface as large as possible, e.g. of inverters and RFI filters.
- Use central earthing points.

The following example shows the effective wiring.



Low-capacitance motor cable
 $C\text{-core/core/C-core/shield} < 75/150 \text{ pF/m} \leq 2.5 \text{ mm}^2 (\geq \text{AWG } 14)$
 $C\text{-core/core/C-core/shield} < 150/300 \text{ pF/m} \geq 4 \text{ mm}^2 (\leq \text{AWG } 12)$

Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)



1-phase mains connection 120 V (90 V ... 132 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxA				
Rated power	kW	0.37	0.75 ... 1.1	0.37 ... 1.1	0.37	0.75 ... 1.1
Connection		Mains connection X100		PE connection	Motor connection X105	
Connection type		Screw terminal		Screw	Screw terminal	
Max. cable cross-section	mm ²	4	4	6	4	4
Stripping length	mm	10	10	10	10	10
Tightening torque	Nm	0.5	0.5	2	0.5	0.5
Required tool		⊖ 1.2 x 8.0	⊖ 0.6 x 3.5	⊕ TX20	⊖ 1.2 x 8.0	⊖ 0.6 x 3.5

Rated data and fusing data

Inverter		I55AP		
		137A	175A	211A
Rated power	kW	0.37	0.75	1.1
Rated output current (8 kHz)	A	2.4	4.2	6
Max. output current (≤ 8 kHz) *	A	4.8	8.4	12
Operation without mains choke				
Rated mains current	A	9.6	16.8	22.9
Fuse (EN 60204-1)				
Characteristic		gG/gL or gRL		
Max. rated current	A	32	32	32
Max. short-circuit current (SCCR)	kA	5	5	5
Circuit breaker (EN 60204-1)				
Characteristic		B		
Max. rated current	A	32	32	32
Max. short-circuit current (SCCR)	kA	5	5	5
Residual current device (RCD)		≥ 30 mA, type B		

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



1-phase mains connection 230/240 V (170 V ... 264 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxB (1-phase), I55APxxxD (1/3-phase)		
Rated power	kW	0.37 ... 2.2		
Connection		Mains connection X100	PE connection	Motor connection X105
Connection type		Screw terminal	Screw	Screw terminal
Max. cable cross-section	mm ²	4	10	4
Stripping length	mm	10	10	10
Tightening torque	Nm	0.5	2	0.5
Required tool		⊖ 1.2 x 8.0	⊕ TX20	⊖ 1.2 x 8.0

Rated data (Heavy Duty) und fusing data

Inverter		I55AP											
		137B	137D	155B	155D	175B	175D	211B	211D	215B	215D	222B	222D
Rated power	kW	0.37		0.55		0.75		1.1		1.5		2.2	
Rated output current (8 kHz)	A	2.4		3.2		4.2		6		7		9.6	
Max. output current (≤ 8 kHz) *	A	4.8		6.4		8.4		12		14		19.2	
Operation without mains choke													
Rated mains current	A	5.7		7.6		10		14.3		16.7		22.5	
Fuse (EN 60204-1)													
Characteristic		gG/gL or gRL											
Max. rated current	A	40		40		40		40		40		40	
Max. short-circuit current (SCCR)	kA	65		65		65		65		65		65	
Circuit breaker (EN 60204-1)													
Characteristic		B											
Max. rated current	A	32		32		32		32		32		32	
Max. short-circuit current (SCCR)	kA	5		5		5		5		5		5	
Residual current device (RCD)		≥ 30 mA, type B											

Rated data (Light Duty) – Data only applies to devices with Protection class IP31/NEMA 1

Inverter		I55AP					
		137D	155D	175D	211D	215D	222D
Rated power	kW	0.55	0.75	1.1	1.5	2.2	3
Rated output current (4 kHz)	A	2.9	3.8	5	7.2	8.4	11.5
Max. output current *	A	4.8	6.4	8.4	12	14	19.2

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



3-phase mains connection 230/240 V (195 V ... 264 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxD (1/3-phase), I55APxxxC (3-phase)															
Rated power	kW	0.37 ... 0.75	1.1 ... 5.5	7.5 ... 11	15 ... 18.5	30	45	0.37 ... 5.5	7.5 ... 11	15 ... 18.5	30 ... 45	0.37 ... 0.75	1.1 ... 5.5	7.5 ... 11	15 ... 18.5	30	45
Connection		Mains connection X100						PE connection				Motor connection X105					
Connection type		Screw terminal						Screw		Bolt		Screw terminal					
Max. cable cross-section	mm ²	4	6	16	35	50	95	6	16	25	95	4	6	16	35	50	95
Stripping length	mm	10	9	11	18	19	22	10	11	16	-	10	9	11	18	19	22
Tightening torque	Nm	0.5	0.5	1.2	3.8	4	10	2	3.4	4	10	0.5	0.5	1.2	3.8	4	10
Required tool		⊖ 1.2 x 8.0	⊖ 0.6 x 3.5	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0	⊕ TX20	⊕ PZ2	⊕ PZ2	⊕ 13	⊖ 1.2 x 8.0	⊖ 0.6 x 3.5	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0

Rated data (Heavy Duty) und fusing data

Inverter		I55AP															
		137D	155D	175D	211D	215D	222D	230C	240C	255C	275C	311C	315C	318C	330C	345C	
Rated power	kW	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	30	45	
Rated output current (8 kHz)	A	2.4	3.2	4.2	6	7	9.6	12	16.5	23	29	42	54	68	89	150	
Max. output current (≤ 8 kHz) *	A	4.8	6.4	8.4	12	14	19.2	24	33	46	58	84	108	136	178	300	
Operation without mains choke																	
Rated mains current	A	3.9	4.8	6.4	7.8	9.5	13.6	15	20.6	28.8	36.3	52.2	62	78	80	135	
Fuse (EN 60204-1)																	
Characteristic		gG/gL or gRL															gG/gL, gR
Max. rated current	A	40	40	40	40	40	40	80	80	80	80	80	125	125	125	200	
Max. short-circuit current (SCCR)	kA	65	65	65	65	65	65	65	5	5	5	5	5	5	10	10	
Circuit breaker (EN 60204-1)																	
Characteristic		B															
Max. rated current	A	32	32	32	32	32	32	80	80	80	80	80	125	125	125	200	
Max. short-circuit current (SCCR)	kA	5	5	5	5	5	5	5	5	5	5	5	5	5	10	10	
Residual current device (RCD)		≥ 30 mA, type B														≥ 300 mA, type B	

Rated data (Light Duty) – Data only applies to devices with Protection class IP31/NEMA 1

Inverter		I55AP															
		137D	155D	175D	211D	215D	222D	230C	240C	255C	275C	311C	315C	318C	330C	345C	
Rated power	kW	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	-	18.5	22	-	-	
Rated output current (4 kHz)	A	2.9	3.8	5	7.2	8.4	11.5	14.4	19.8	27.6	34.8	-	64.8	81.6	-	-	
Max. output current *	A	4.8	6.4	8.4	12	14	19.2	24	33	46	58	-	108	136	-	-	

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



3-phase mains connection 400 V (340 V ... 528 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxF														
Rated power	kW	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 45	55 ... 75	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 75	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 45	55 ... 75	
Connection		Mains connection X100					PE connection					Motor connection X105				
Connection type		Screw terminal					Screw			Bolt	Screw terminal					
Max. cable cross-section	mm ²	4	16	35	50	95	6	16	25	95	4	16	35	50	95	
Stripping length	mm	10	11	18	19	22	10	11	16	-	10	11	18	19	22	
Tightening torque	Nm	0.5	1.2	3.8	4	10	2	3.4	4	10	0.5	1.2	3.8	4	10	
Required tool		⊖ 1.2 x 8.0	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0	⊕ TX20	⊕ TX20	⊕ PZ2	⊕ 13	⊖ 0.6 x 3.5	⊖ 1.2 x 8.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0	

Rated data (Heavy Duty) und fusing data

Inverter		I55AP																		
		137F	155F	175F	211F	215F	222F	230F	240F	255F	275F	311F	315F	318F	322F	330F	337F	345F	355F	375F
Rated power	kW	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22	30	37	45	55	75
Rated output current (8 kHz)	A	1.3	1.8	2.4	3.2	3.9	5.6	7.3	9.5	13	16.5	23.5	32	40	47	61	76	89	110	150
Max. output current (≤ 8 kHz) *	A	2.6	3.6	4.8	6.4	7.8	11.2	14.6	19	26	33	47	64	80	94	122	152	178	220	300
Operation without mains choke																				
Rated mains current	A	1.8	2.5	3.3	4.4	5.4	7.8	9.6	12.5	17.2	20	28.4	37	46	53	54.9	68	80	99	135
Fuse (EN 60204-1)		gG/gL or gRL																		
Characteristic																				gR
Max. rated current	A	32	32	32	32	32	32	50	50	50	50	50	80	80	80	125	125	125	200	200
Max. short-circuit current (SCCR)	kA	65	65	65	65	65	65	5	5	5	5	5	5	5	5	10	10	10	10	10
Circuit breaker (EN 60204-1)		B																		
Characteristic																				
Max. rated current	A	32	32	32	32	32	32	50	50	50	50	50	80	80	80	125	125	125	200	200
Max. short-circuit current (SCCR)	kA	5	5	5	5	5	5	5	5	5	5	5	5	5	5	10	10	10	10	10
Residual current device (RCD)		≥ 30 mA, type B											≥ 300 mA, type B							

Rated data (Light Duty) – Data only applies to devices with Protection class IP31/NEMA 1

Inverter		I55AP																		
		137F	155F	175F	211F	215F	222F	230F	240F	255F	275F	311F	315F	318F	322F	330F	337F	345F	355F	375F
Rated power	kW	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22	30	-	-	-	-	-
Rated output current (4 kHz)	A	1.6	2.2	2.9	3.8	4.7	6.7	8.8	11.9	15.6	23	28.2	38.4	48	56.4	-	-	-	-	-
Max. output current *	A	2.6	3.6	4.8	6.4	7.8	11.2	14.6	19	26	33	47	64	80	94	-	-	-	-	-

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



3-phase mains connection 480 V (340 V ... 528 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxF														
Rated power	kW	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 45	55 ... 75	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 75	0.37 ... 5.5	7.5 ... 11	15 ... 22	30 ... 45	55 ... 75	
Connection		Mains connection X100					PE connection					Motor connection X105				
Connection type		Screw terminal					Screw			Bolt	Screw terminal					
Max. cable cross-section	mm ²	4	16	35	50	95	6	16	25	95	4	16	35	50	95	
Stripping length	mm	10	11	18	19	22	10	11	16	-	10	11	18	19	22	
Tightening torque	Nm	0.5	1.2	3.8	4	10	2	3.4	4	10	0.5	1.2	3.8	4	10	
Required tool		⊖ 1.2 x 8.0	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0	⊕ TX20	⊕ TX20	⊕ PZ2	⊕ 13	⊖ 0.6 x 3.5	⊖ 1.2 x 8.0	⊖ 0.8 x 4.5	⊕ 4.0	⊕ 6.0	

Rated data (Heavy Duty) und fusing data

Inverter		I55AP																		
		137F	155F	175F	211F	215F	222F	230F	240F	255F	275F	311F	315F	318F	322F	330F	337F	345F	355F	375F
Rated power	kW	0.37	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22	30	37	45	55	75
Rated output current (8 kHz)	A	1.1	1.6	2.1	3	3.5	4.8	6.3	8.2	11	14	21	27	34	40.4	52	65	77	96	124
Max. output current (≤ 8 kHz) *	A	2.2	3.2	4.2	6	7	9.6	12.6	16.4	22	28	42	54	68	80.8	104	130	154	192	248
Operation without mains choke																				
Rated mains current	A	1.5	2.1	2.8	3.7	4.5	6.5	8	10.5	14.3	16.6	23.7	30.7	38	44.2	45.7	57	66.7	83	113
Fuse (EN 60204-1)																				
Characteristic		gG/gL or gRL																	gR	
Max. rated current	A	32	32	32	32	32	32	50	50	50	50	50	80	80	80	125	125	125	200	200
Max. short-circuit current (SCCR)	kA	65	65	65	65	65	65	5	5	5	5	5	5	5	5	10	10	10	10	10
Circuit breaker (EN 60204-1)																				
Characteristic		B																		
Max. rated current	A	32	32	32	32	32	32	50	50	50	50	50	80	80	80	125	125	125	200	200
Max. short-circuit current (SCCR)	kA	5	5	5	5	5	5	5	5	5	5	5	5	5	5	10	10	10	10	10
Residual current device (RCD)		≥ 30 mA, type B											≥ 300 mA, type B							

Rated data (Light Duty) – Data only applies to devices with Protection class IP31/NEMA 1

Inverter		I55AP																		
		137F	155F	175F	211F	215F	222F	230F	240F	255F	275F	311F	315F	318F	322F	330F	337F	345F	355F	375F
Rated power	kW	0.55	0.75	1.1	1.5	2.2	3	4	5.5	7.5	11	15	18.5	22	30	-	-	-	-	-
Rated output current (4 kHz)	A	1.3	1.9	2.5	3.6	4.2	5.8	7.6	9.8	13.2	18.3	25.2	32.4	40.8	48.5	-	-	-	-	-
Max. output current *	A	2.2	3.2	4.2	6	7	9.6	12.6	16.4	22	28	42	54	68	80.8	-	-	-	-	-

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



3-phase mains connection 600 V (425 V ... 660 V, 45 Hz ... 65 Hz)

Terminal data

Inverter		I55APxxxG								
Rated power	kW	0.75 ... 5.5	7.5 ... 11	15 ... 22	0.75 ... 5.5	7.5 ... 11	15 ... 22	0.75 ... 5.5	7.5 ... 11	15 ... 22
Connection		Mains connection X100			PE connection			Motor connection X105		
Connection type		Screw terminal			Screw			Screw terminal		
Max. cable cross-section	mm ²	4	16	35	6	16	25	4	16	35
Stripping length	mm	10	11	18	10	11	16	10	11	18
Tightening torque	Nm	0.5	1.2	3.8	2	3.4	4	0.5	1.2	3.8
Required tool		⊖ 1.2 x 8.0	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5	⊕ TX20	⊕ PZ2	⊕ PZ2	⊖ 1.2 x 8.0	⊖ 0.8 x 4.0	⊖ 0.8 x 4.5

Rated data (Heavy Duty) und fusing data

Inverter		I55AP									
		175G	215G	222G	240G	255G	275G	311G	315G	318G	322G
Rated power	kW	0.75	1.5	2.2	4	5.5	7.5	11	15	18.5	22
Rated output current (8 kHz)	A	1.7	2.7	3.9	6.1	9	11	17	22	27	32
Max. output current (≤ 8 kHz) *	A	3.4	5.4	7.8	12.2	18	22	34	44	54	64
Operation without mains choke											
Rated mains current	A	2.0	3.2	4.4	6.8	10.2	12.4	19.7	25	31	36
Fuse (EN 60204-1)											
Characteristic		gG/gL or gRL									
Max. rated current	A	20	20	20	40	40	40	40	60	60	60
Max. short-circuit current (SCCR)	kA	65	65	65	5	5	5	5	5	5	5
Circuit breaker (EN 60204-1)											
Characteristic		-									
Max. rated current	A	-	-	-	-	-	-	-	-	-	-
Max. short-circuit current (SCCR)	kA	-	-	-	-	-	-	-	-	-	-
Residual current device (RCD)		≥ 30 mA, type B									

Rated data (Light Duty) – Data only applies to devices with Protection class IP31/NEMA 1

Inverter		I55AP									
		175G	215G	222G	240G	255G	275G	311G	315G	318G	322G
Rated power	kW	1.1	2.2	3	5.5	7.5	11	15	18.5	22	30
Rated output current (4 kHz)	A	2	3.2	4.7	7.9	10.8	13.2	22	27	32.4	41
Max. output current *	A	3.4	5.4	7.8	12.2	18	22	34	44	54	64

* Overload time = 3 s, recovery time = 12 s

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			



EMC filter for motor cable

EMC filters are used to ensure compliance with the EMC requirements in accordance with the EN IEC 61800-3 standard.

For inverters ≥ 30 kW: If compliance with category C2 is to be achieved, an EMC filter for the motor cable is required and the motor cable length must not exceed 15 m. In addition, the parameter "switching frequency" (0x2939) is to be left at the default setting.

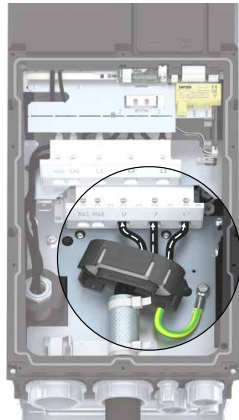
The EMC filter for the motor cable (ferrite core) is installed in the terminal box of the device:



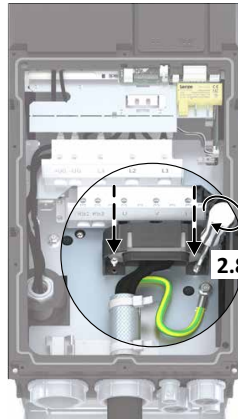
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3



2.8 Nm

Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)



Brake resistor connection

NOTE

Overload

Possible consequences: Irreversible damage to the brake resistor

- Protect the brake resistor of the inverter against overload with suitable parameterization.
- The thermostat of the brake resistor can be used to establish a safety shutdown to disconnect the inverter from the mains.

Recommendation: Use intrinsically safe brake resistors to be able to dispense with a separate switch-off device (e.g. a contactor).

Short connection cables up to 0.5 m	Long connection cables up to max. 5 m
<p>Up to a cable length of 0.5 m, the cable for the brake resistor and that of the temperature monitoring can be twisted. This procedure reduces problems caused by EMC interference.</p>	<p>The cable of the brake resistor must be shielded. The maximum length is 5 m. For the temperature monitoring cable, twisting is sufficient.</p>
<p>① Wiring to the "brake resistor" connection on the inverter or another component with brake chopper.</p>	
<p>② Optional: Wiring to a control contact that is set to monitor the thermal contact. If the thermal contact responds, the voltage supply to the inverter must be disconnected (e.g. switch off the control of the mains contactor).</p>	

Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)

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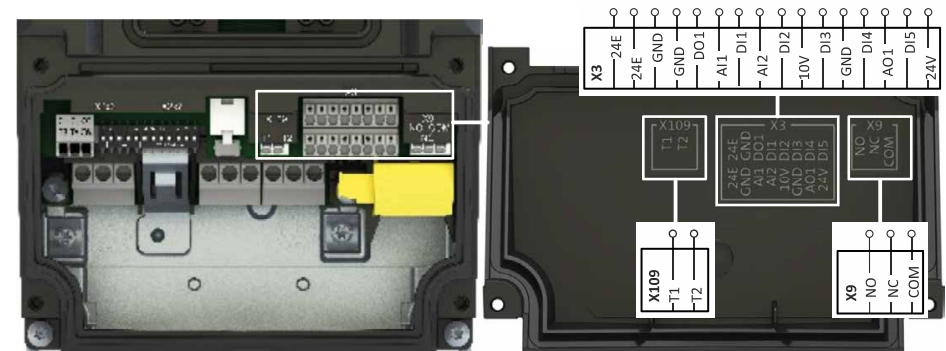
Control terminals X3

Connection type		Spring terminal, not pluggable
Max. cable cross-section	mm ²	1.5
Stripping length	mm	9
Required tool		⊖ 0.4 x 2.5
Application	DI1 DI2 DI3 DI4 DI5	Digital inputs DI3/DI4 can optionally be used as frequency input or encoder input. HIGH active/LOW active switchable LOW = 0 ... +3 V HIGH = +12 V ... +30 V
	DO1	Digital output Max. 100 mA for DO1 and 24 V output
	AI1 AI2	Analog inputs Can optionally be used as voltage inputs or current inputs.
	AO1	Analog output Can optionally be used as voltage output or current output.
	24E	24 V input For mains-independent power DC supply of control electronics (including communication). Max. 1 A
	10V 24V	10 V output Primarily for the supply of a potentiometer (1 ... 10 kΩ). Max. 10 mA 24 V output Primarily for the supply of digital inputs. Max. 100 mA for DO1 and 24 V output

NOTE

For voltage supply with DC 24 V (± 20 %), use only a safely separated power supply unit in accordance with prevailing SELV/PELV requirements.

The terminal designations can be found on the inside of the cover.



Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)

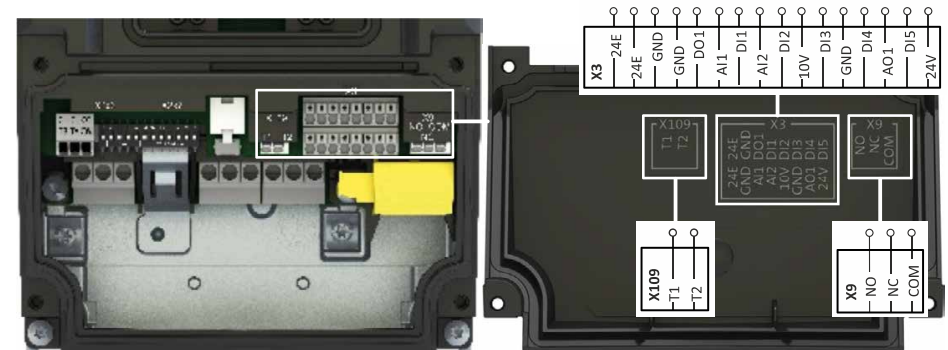


Relay output X9

The relay is not suitable for direct switching of an electromechanical holding brake. Use a corresponding suppressor circuit in case of an inductive or capacitive load.

Connection type		Spring terminal, not pluggable
Max. cable cross-section	mm ²	1.5
Stripping length	mm	9
Required tool		⊖ 0.4 x 2.5
Application	NO	Normally-open contact
	NC	Normally-closed contact
	COM	Common contact
Max. switching voltage/switching current		AC 240 V/3 A
		DC 24 V/2 A
		DC 240 V/0.16 A

The terminal designations can be found on the inside of the cover.



Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)

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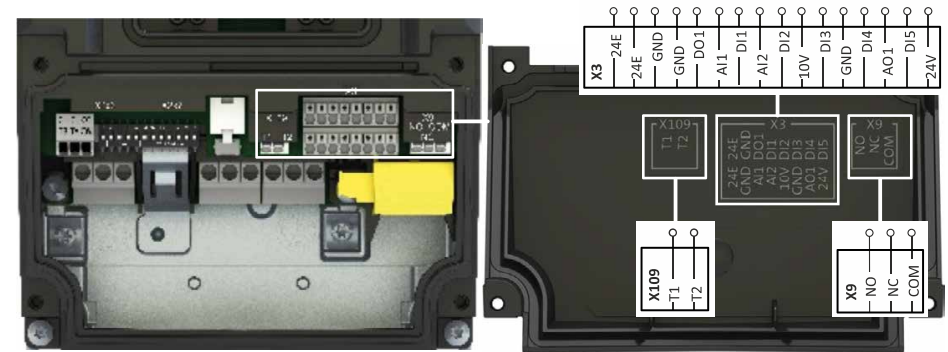
PTC input X109 *

In the default setting, the motor temperature monitoring is active! By default, a wire jumper is installed between the terminals T1 and T2. Before connecting a thermal sensor, remove the wire jumper.

Connection type		Spring terminal, not pluggable
Max. cable cross-section	mm ²	1.5
Stripping length	mm	9
Required tool		⊖ 0.4 x 2.5
Application	T1 T2	Connection of PTC or thermal contact
Sensor types		PTC single sensor (DIN 44081)
		PTC triplet sensor (DIN 44082)
		Thermal contact










* Devices for a rated mains voltage of 600 V do not have a PTC input.

The terminal designations can be found on the inside of the cover.



Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)

Networks

Network		CANopen	Modbus RTU	IO-Link	EtherCAT	EtherNet/IP	Modbus TCP	PROFINET
Connection		X216		X316	X246 X247	X266 X267	X276 X277	X256 X257
Connection type		Spring terminal, not pluggable			RJ45	RJ45	RJ45	RJ45
Max. cable cross-section	mm ²	1.5			-	-	-	-
Stripping length	mm	9			-	-	-	-
Required tool		⊖ 0.4 x 2.5			-	-	-	-

CANopen / Modbus RTU

The network must be terminated with a resistor at the first and last physical node. At these nodes, set the DIP switch "R" to ON.

You can use the other DIP switches to set the node address and baud rate.
When these DIP switches are all in the OFF position: Node address = setting in P510.01, baud rate = setting in P510.02. For Modbus RTU, the baud rate and parity are detected automatically in OFF position.

EtherCAT

You can set the EtherCAT identifier for "Explicit Device Identification" using the rotary encoder switches. When both are in position 0: Identifier = setting in P510.04.

Ethernet/IP / Modbus TCP










You can set the last byte of the IP address using the rotary encoder switches:
192.168.124.<switch position>. When both are in position 0: IP address = setting in P510.01.

PROFINET


The rotary encoder switches have no function.

Electrical installation

Preparation	Cable glands	Connection diagram	1-phase 120 V	1-phase 230/240 V	3-phase 230/240 V	3-phase 400 V	3-phase 480 V	3-phase 600 V	EMC filter motor cable
Brake resistor	Control terminals	Relay output	PTC input	Networks	Functional safety	Safe torque off (STO)			

Functional safety

 **DANGER!**

Uncontrolled start-up

Improper installation of the safety engineering system can cause an uncontrolled starting action of the drives.

Possible consequences: Death or severe injuries

- Safety engineering systems may only be installed and commissioned by qualified personnel.
- All wiring must be EMC-compliant.
- All control components (switches, relays, PLC, ...) must comply with the requirements of EN ISO 13849-1 and EN ISO 13849-2.
- Switches, relays with at least IP54 enclosure.
- Devices with a degree of protection less than IP54 must always be installed in a control cabinet with a minimum protection class of IP54.
- The wiring must be shielded.
- It is essential to use insulated wire end ferrules for wiring.
- All safety-relevant cables outside the control cabinet must be protected, e.g. by means of a cable duct.
- Securely eliminate short-circuits and crossed wires according to the specifications of EN ISO 13849-2.
- Please refer to EN ISO 13849-1 and EN ISO 13849-2 for all further requirements and measures.
- In the case of an external force effect on the drive axes, additional brakes are necessary. In particular, please observe the effect of gravitational force on hanging loads!
- For safety-related braking functions, use safety-rated brakes only.
- The user must ensure that the inverter is only operated within the specified environmental conditions in its intended application. Only by doing so can the specified safety-related characteristics be adhered to.

NOTE

Automatic restart

when the requirement of the safety function is disabled.

Possible consequences: Death or severe injuries

- You must implement external measures in accordance with EN ISO 13849-1 to ensure that the drive only starts up again after an acknowledgment.

NOTE

Overvoltage

Possible consequences: Destruction of the safety component

- Make sure that the maximum voltage (maximum rated) at the safe inputs does not exceed 32 V DC.

NOTE

Excessive humidity or condensation

Possible consequences: Malfunction or irreparable damage to safety component

- Only commission the safety component when it has acclimatized.

Electrical installation

- Preparation
- Cable glands
- Connection diagram
- 1-phase | 120 V
- 1-phase | 230/240 V
- 3-phase | 230/240 V
- 3-phase | 400 V
- 3-phase | 480 V
- 3-phase | 600 V
- EMC filter motor cable
- Brake resistor
- Control terminals
- Relay output
- PTC input
- Networks
- Functional safety
- Safe torque off (STO)



Safe torque off (STO)

⚠ DANGER!

No "Emergency switching off" in accordance with EN 60204-1

When using the "Safe torque off (STO)" function, additional measures are required for an "Emergency switching off" in accordance with EN 60204-1. There is no electrical isolation between the motor and inverter, no service switch or maintenance switch!

Possible consequences: Death or severe injuries

- An "Emergency switching off" requires an electrical isolation, e.g. by a central mains contactor.

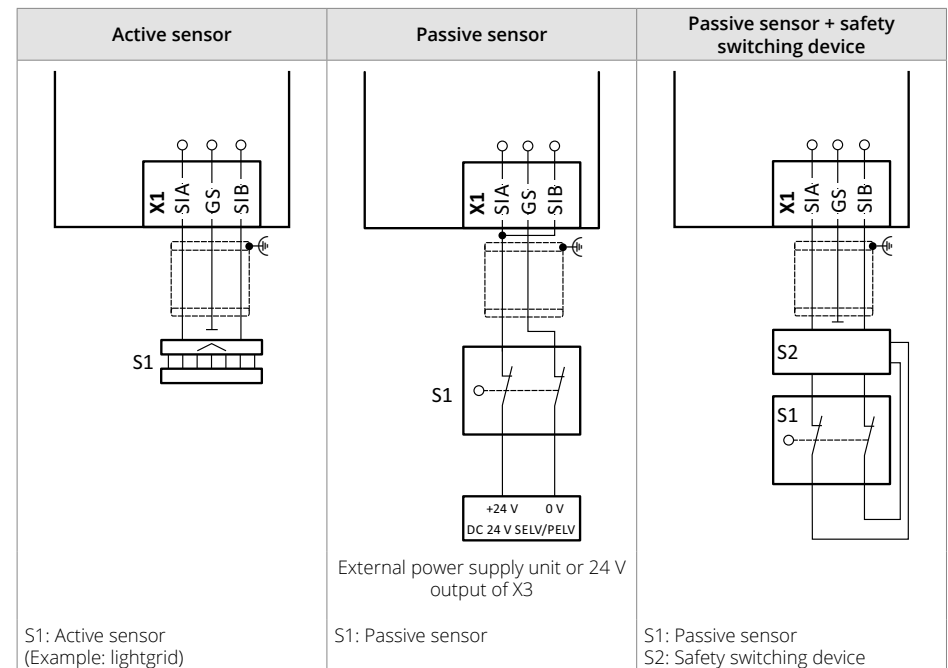
Control terminals X1

Connection type		Spring terminal, pluggable
Max. cable cross-section	mm ²	1.5
Stripping length	mm	9
Required tool		⊖ 0.4 x 2.5
Application	SIA SIB	Inputs for connecting active or passive sensors
	GS	Reference potential for SIA and SIB

Specifications for SIA, SIB		minimum	typical	maximum
LOW signal	V	-3	0	+5
HIGH signal	V	+15	+24	+30
Runtime	ms		3	
Switch-off time	ms		50	60
Input current SIA	mA		10	14
Input current SIB	mA		7	12
Input peak current	mA		100	
Test pulse duration	ms			1
Test pulse interval	ms	10		

Connection of active and passive sensors

















The connection diagrams shown are only example circuits. The user is responsible for the correct safety-related design and selection of the components!



Safety-related characteristic values and further example circuits can be found in the project planning document.

Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

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Initial switch-on

DANGER!

Unexpected states during commissioning

Incorrect wiring can cause unexpected states during the commissioning phase.
Possible consequences: Death, severe injuries, or damage to property

- Wiring must be complete and correct.
- Wiring must be free of short circuits and earth faults.
- The motor circuit configuration (star/delta) must be adapted to the inverter.
- The motor must be connected in-phase (rotating direction).
- The "emergency off" function of the overall system must operate correctly.
- Clear hazardous area.
- Observe safety instructions and safety clearances.

















Preconditions:

- The power connections must be wired.
- The digital inputs X3/DI1 (start/stop), X3/DI3 (reversal) and X3/DI4 (frequency preset 20 Hz) must be wired.
- The analog input X3/AI1 must not be wired or connected to GND.


1. Switch on mains voltage.
2. Check readiness for operation.
3. Observe LED status displays "RDY" and "ERR" on the inverter front panel.

Commissioning

- Initial switch-on
 - Important notes**
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

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Important notes

 **DANGER!**

Unexpected and dangerous motor movements and system movements

Incorrect settings during commissioning may cause unexpected and dangerous motor and system movements.

Possible consequences: Death, severe injuries, or damage to property

- Clear hazardous area.
- Observe safety instructions and safety clearances.

Instead of the keypad module, the inverter is also available with the following accessories from the factory:

- WLAN module
- without module

Keypad module

Commissioning with the keypad module is described on the following pages.

WLAN module

A connection to the WLAN module is established upon entering the connection data.

Default setting:

- IP address: 192.168.178.1
- SSID: "Product type"_"10-digit identification"
- WLAN password: password

Micro USB port

The inverter has a built-in micro USB port.

- The micro USB port may only be used temporarily for the diagnostics and parameterization of the inverter. We recommend keeping the inverter and diagnostics device on the same ground potential or disconnecting the diagnostics device from the mains.

Engineering Tool »EASY Starter«


Commissioning and diagnostics can be carried out with the »EASY Starter« engineering tool. For communication, a standard USB cable (A plug to micro B plug) is required.

SMART Keypad App


The Lenze SMART Keypad App for Android or iOS allows you to diagnose and parameterize an inverter. A WLAN module on the inverter is required for communication.

- Ideal for the parameterization of simple applications such as a conveyor belt.
- Ideal for the diagnostics of the inverter.

The app can be found in the Google Play Store or in the Apple App Store.



Android



iOS

Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions



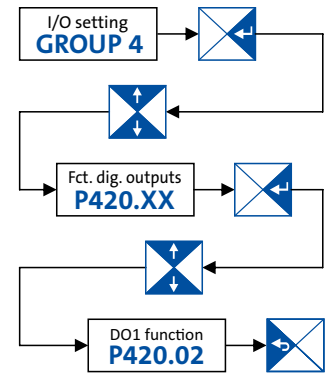
Keypad module – Functions of the keys

Key	Actuation	Action
Up arrow key Down arrow key	press briefly	<ul style="list-style-type: none"> · Navigation in the menu · Parameter alteration
Enter key	press briefly	<ul style="list-style-type: none"> Go to Menu/Parameter · Confirm parameter
	press and hold for 3s	Save parameter ("P.SAVED" appears on screen when parameter is saved.)
Back key	press briefly	Quit Menu/Parameters
CTRL key	press briefly	Activate keypad control
Start key	press briefly	Start motor
R/F key	press briefly	Change rotating direction
Stop key	press briefly	Stop motor

- The motor must be at standstill before parameters can be changed or confirmed.
- The settings are saved temporarily until the motor is switched off again. Press and hold the enter key for 3 s to save the settings permanently.


Example of the keypad handling

Function assignment for digital output DO1 with parameter P420.02:



Commissioning


- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions



Keypad control


Activate temporary keypad control:

1. Press the CTRL key to activate the keypad control.
2. Press the enter key to confirm the change.



Deactivate temporary keypad control:


1. Press the CTRL key to deactivate the keypad control.
2. Press the enter key to confirm the change.



Activate permanent keypad control:


If the keypad does not have a CTRL key, the motor control is activated via the following parameters:

- Set P200.00 to 1.
- Set P201.01 to 1.
- Set P400.01 to 1.
- Set P400.02 to 1.




Start/control/stop motor with keypad:

1. Press the start key to start the motor.
 - The keypad shows the motor speed.
2. Change the frequency setpoint using the up arrow key or the down arrow key.
3. Press the stop key to stop the motor.




Reverse rotating direction:


1. Press the R/F key.
2. Press the enter key to confirm the reversal of rotating direction.




Additional functions




Additional functions




Additional functions




Additional functions




Additional functions




Additional functions



Additional functions



Additional functions



Additional functions

Commissioning

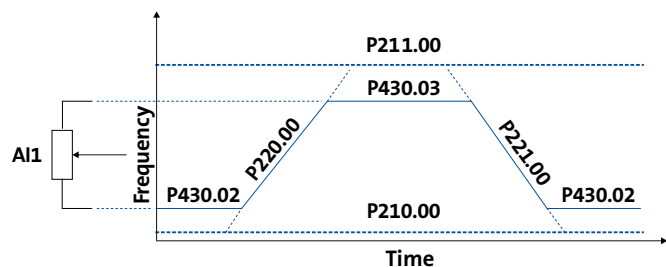
- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions



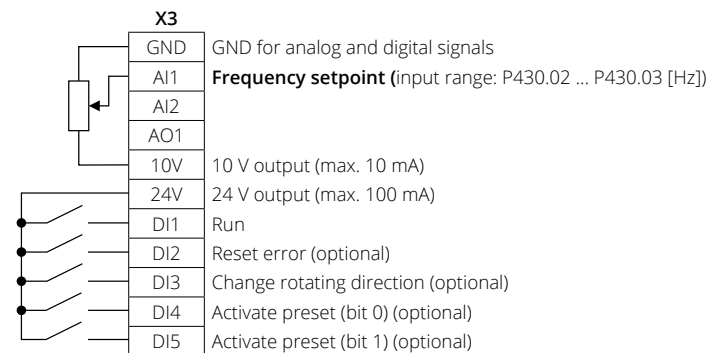
Quick commissioning – terminal control

The following quick overview with graphical parameter representation is sufficient for commissioning many applications with terminal control. Further setting options are described in this document or in the commissioning document.

1. Load default setting: Set P700.01 to 1.
2. Set the following parameters for V/f characteristic control:
 - P208.01: Mains voltage
 - P303.01: V/f characteristic data: Base voltage
 - P303.02: V/f characteristic data: Base frequency
 - P210.00: Minimum frequency
 - P211.00: Maximum frequency
 - P220.00: Acceleration time 1
 - P221.00: Deceleration time 1
 - P430.02: Analog input 1: Min frequency value
 - P430.03: Analog input 1: Max frequency value



3. Save settings: Press and hold the enter key for 3 s.
4. With the wiring shown on the right, the inverter can be operated using the control terminals.



Preset 1 is activated if DI4 is connected.
 Preset 2 is activated if DI5 is connected.
 Preset 3 is activated if DI4 and DI5 are connected at the same time.

Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

Extended terminal control

The following illustration shows a more extensive wiring of the control terminals linked with the respective parameters.

Default setting

P201.01
(configured AI1 as standard setpoint)

P400.02 Run

P400.04 Reset error

P400.13 Change rotating direction

P400.18 Activate preset (bit 0)

P400.19 Activate preset (bit 1)

P420.02 DO1 triggered at "releasing the brake"

P420.01 Relay triggered at "ready for operation"

X3

24E Optional external 24 V supply

GND GND for analog and digital signals

AI1 Analog input 1

AI2 Analog input 2

AO1 Analog output 1

10V 10 V output (max. 10 mA)

24V 24 V output (max. 100 mA)

DI1 Digital input 1

DI2 Digital input 2

DI3 Digital input 3

DI4 Digital input 4

DI5 Digital input 5

DO1 Digital output 1

GND GND for analog and digital signals

X9

NO Relay NO contact

NC Relay NC contact

COM Relay center contact


Setpoint selection and configuration:

DI5	DI4	Setpoint	Configuration	Default setting	
0	0	Analog input 1	P430.01	AI1 input area	0 ... 10 VDC
			P430.02	AI1 freq @ min	0.0 Hz
			P430.03	AI1 freq @ max	50.0 Hz / 60.0 Hz*
0	1	Preset value 1	P450.01	Freq. preset 1	20.0 Hz
1	0	Preset value 2	P450.02	Freq. preset 2	40.0 Hz
1	1	Preset value 3	P450.03	Freq. preset 3	50.0 Hz / 60.0 Hz*

* Depending on whether device is for 50-Hz mains or 60-Hz mains


Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions




The most important parameters at a glance

This chapter contains the most important parameters and selections.




You can find a detailed description in the commissioning document:
www.lenze.com/product-information




The parameters are divided into the following function groups:


- Pxxx.xx group 0: Favorites
- P1xx.xx group 1: Diagnostics
- P2xx.xx group 2: Basic setting
- P3xx.xx group 3: Motor control
- P4xx.xx group 4: I/O setting
- P5xx.xx group 5: Network setting
- P6xx.xx group 6: Process controller
- P7xx.xx group 7: Additional functions
- P8xx.xx group 8: Sequencer





Favorites (group 0)


Group 0 contains the configurable favorites that are also contained in the groups 1 to 4. In the default setting these are the most common parameters for the solution of typical applications.























Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites**
 - Basic setting
 - Motor control
- Additional functions

Display-Code	Name	Possible settings/ Value ranges	Keypad code	Information
P100.00	Output frequency	x.x Hz (read only)		Display of the actual output frequency.
P103.00	Actual current	x.x % (read only)		Display of the actual motor current.
P106.00	Motor voltage	x VAC (read only)		Display of the actual motor voltage.
P150.00	Error code	- (Read only)		Error message.
P200.00	Control selection	Flexible I/O	[0]	This selection enables a flexible assignment of the start, stop, and rotating direction commands with digital signal sources.
		Keypad	[1]	This selection enables the motor to start exclusively via the start key of the keypad. Other signal sources for starting the motor are ignored.
P201.01	F-setp.source	Keypad	[1]	The setpoint is specified locally by the keypad.
		Analog input 1	[2]	The setpoint is defined as analog signal via the analog input 1.
		Analog input 2	[3]	The setpoint is defined as analog signal via the analog input 2.
		HTL input	[4]	The digital inputs DI3 and DI4 can be configured as HTL input to use an HTL encoder as setpoint encoder or define the setpoint as a reference frequency ("pulse train").
		Network	[5]	The setpoint is defined as process data object via the network.
P203.01	Start method	Frequency preset 1 ... 15	[11] ... [25]	For the setpoint selection, "preset" values can be parameterized and selected. All frequency presets are described in detail in the commissioning manual.
		Normal	[0]	After start command, the standard ramps are active.
		DC braking	[1]	After start command, the "DC braking" function is active for the time set in P704.02.
		Flying restart circuit	[2]	After the start command, the flying restart circuit is active.
P203.03	Stop method	Premagnetization	[3]	After start command, the standard ramps are active and the premagnetization of the motor is activated. This reduces the motor current and smoothes the acceleration curve during the starting process (only relevant in the V/f motor control mode).
		Coasting	[0]	The motor has no torque (coasts down to standstill).
		Standard ramp	[1]	The motor is brought to a standstill with the deceleration time 1 P221.00 (or deceleration time 2 P223.00 if activated).
		Quick stop ramp	[2]	The motor is brought to a standstill with the deceleration time (P225.00) set for the "quick stop" function.
P208.01	Mains voltage	Switch-off positioning	[3]	Is similar to the stop method "standard ramp [1]". Depending on the actual output frequency, however, the inverter delays the beginning of the down-ramping so that the number of motor revolutions until a standstill is reached and thus the stop position is always relatively constant.
		230 Veff	[0]	Selection of the mains voltage for actuating the inverter.
		400 Veff	[1]	
		480 Veff	[2]	
		120 Veff	[3]	
480 Veff (600 V devices)	[5]			
600 Veff	[6]			

* Default setting dependent on the model



Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

Display-Code	Name	Possible settings/ Value ranges	Keypad code	Information
P210.00	Min. Frequency	0.0 ... 599.0 Hz		Lower limit value for all frequency setpoints.
P211.00	Max. frequency	Device for 50-Hz mains: 50 Hz * Device for 60-Hz mains: 60 Hz *		Upper limit value for all frequency setpoints.
P220.00	Acceleration 1	0.0 ... 5.0 ... 3600.0 s		Acceleration time 1.
P221.00	Deceleration 1	0.0 ... 5.0 ... 3600.0 s		Deceleration time 1
P300.00	Motor ctrl mode	Servo control (SC ASM)	[2]	This control mode is used for servo control of an asynchronous motor.
		Sensorless control (SL PSM)	[3]	This control type is used for the sensorless control of a synchronous motor.
		Sensorless vector control (SLVC)	[4]	This control type is used for sensorless vector control of an asynchronous motor.
		V/f characteristic control VFC open loop	[6]	This control mode is used for the speed control of an asynchronous motor via a V/f characteristic and is the simplest control mode.
		V/f characteristic control (VFC closed loop)	[7]	The control mode is used for speed control of an asynchronous motor via a V/f characteristic with speed feedback.
P302.00	V/f characteristic shape	Linear	[0]	Linear characteristic for drives with constant load torque over the speed.
		Square-law	[1]	Square-law characteristic for drives with a square-law load torque over the speed.
		Eco	[3]	Linear characteristic with energy optimization in the partial load operational range.
P303.01	Base voltage	0 ... 230 ... 5000 V *		Base voltage and base frequency define the V/f ratio and thus the gradient of the V/f characteristic. • The V/f base voltage is usually set to the rated motor voltage. • The V/f base frequency is usually set to the rated motor frequency.
P303.02	Base frequency	Device for 50-Hz mains: 50 Hz * Device for 60-Hz mains: 60 Hz *		
P304.00	Limitation of rotation	Only clockwise (CW)	[0]	The motor can only be rotated clockwise (CW). The transfer of negative frequency and PID setpoints to the motor control is prevented.
		Both rotation directions	[1]	Both directions of motor rotation are enabled.
P305.00	Switching frequency	8 kHz var/opt/4 *		Selection of the inverter switching frequency.
P306.01	Overload selection	Heavy duty	[0]	Load characteristic for high dynamic requirements.
		Light Duty	[1]	Load characteristic for low dynamic requirements.
P308.01	Max.load for 60s	30 ... 150 ... 200 %		Maximum permissible thermal motor utilization (max. permissible motor current for 60 seconds). With regard to rated motor current (P323.00).
P316.01	Fixed V/f boost	0.0 ... 2.5 ... 20.0 % *		Constant voltage boost for the V/f characteristic control without feedback.
P323.00	Rated. mot curr.	0.001 ... 1.700 ... 500.000 A *		Setting of the rated motor current according to motor nameplate.
P324.00	Max. current	0.0 ... 200.0 ... 3000.0 %		Maximum overload current of the inverter. With regard to rated motor current (P323.00).
P400.01	Inverter enable	TRUE	[1]	Assignment of a trigger to the "inverter enable" function. Trigger = TRUE: The inverter is enabled (unless there is another cause for inverter disable). Trigger = FALSE: The inverter is disabled. The motor has no torque and coasts.

* Default setting dependent on the model



Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

Display-Code	Name	Possible settings/ Value ranges	Keypad code	Information
Favorites (group 0)				
P400.02	Run	Digital input 1	[11]	<p>Assignment of a trigger to the "Run" function.</p> <p>Function 1: Start / stop motor (default setting) Function 1 is active if no further start commands (start forward/start reverse) have been connected to triggers, no keypad control is active and no network control is active. Trigger = TRUE: Let motor rotate forward (CW). Trigger = FALSE: Stop motor according to stop function (P203.03).</p> <p>Function 2: Start enable/stop motor Function 2 is active if further start commands have been connected to triggers, the keypad control is active or the network control is active. Trigger = TRUE: Start commands of the active control source are enabled. Trigger = FALSE: Stop motor.</p>
P400.03	Quick stop	Not connected	[0]	<p>Assignment of a trigger to the "Activate quick stop" function. Trigger = TRUE: Activate quick stop. Quick stop ramp adjustable in P225.00. Trigger = FALSE: Deactivate quick stop</p>
P400.04	Error reset	Digital input 2	[12]	<p>Assignment of a trigger to the "Reset error" function. Trigger = FALSE > TRUE (edge): Active error is reset (acknowledged) if the error condition is not active anymore and the error is resettable. Trigger = FALSE: No action.</p>
P400.05	DC braking	Not connected	[0]	<p>Assignment of a trigger to the "Activate DC braking" function. Trigger = TRUE: Activate DC braking. Trigger = FALSE: Deactivate DC braking.</p>
P400.06	Start forward	Not connected	[0]	<p>Assignment of a trigger to the "Start forward (CW)" function. Trigger = FALSE > TRUE (edge): Let motor rotate forward. Trigger = TRUE > FALSE (edge): No action. Stop via P400.02 (default setting of digital input 1).</p>
P400.07	Start reverse	Not connected	[0]	<p>Assignment of a trigger to the "Start reverse (CCW)" function. Trigger = FALSE > TRUE (edge): Let motor rotate backward. Trigger = TRUE > FALSE (edge): No action. Stop via P400.02 (default setting of digital input 1).</p>
P400.08	Run forward	Not connected	[0]	<p>Assignment of a trigger to the "Run forward (CW)" function. Trigger = TRUE: Let motor rotate forward. Trigger = FALSE: Stop motor.</p>
P400.09	Run reverse	Not connected	[0]	<p>Assignment of a trigger to the "Run reverse (CCW)" function. Trigger = TRUE: Let motor rotate backward. Trigger = FALSE: Stop motor.</p>
P400.13	Reverse rot. dir.	Digital input 3	[13]	<p>Assignment of a trigger to the "Reverse rotating direction" function. Trigger = TRUE: The setpoint specified is inverted (i.e. the sign is inverted). Trigger = FALSE: No action/deactivate function again.</p>

* Default setting dependent on the model

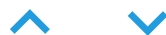


Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions










Display-Code	Name	Possible settings/ Value ranges	Keypad code	Information
P400.18	Setp: Preset B0	Digital input 4	[14]	Assignment of a trigger to the "Activate preset (bit 0)" function. Bit with the valency 2 ⁰ for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1".
P400.19	Setp: Preset B1	Digital input 5	[15]	Assignment of a trigger to the "Activate preset (bit 1)" function. Bit with the valency 2 ¹ for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1".
P400.20	Setp: Preset B2	Not connected	[0]	Assignment of a trigger to the "Activate preset (bit 2)" function. Bit with the valency 2 ² for the bit-coded selection and activation of a parameterized setpoint (preset value). Trigger = FALSE: Bit = "0". Trigger = TRUE: Bit = "1".
P420.01	Relay function	Running	[50]	TRUE if inverter and start are enabled and output frequency > 0.2 Hz. Otherwise FALSE.
		Ready for operation	[51]	TRUE if inverter is ready for operation (no error active, no STO active and DC-bus voltage ok). Otherwise FALSE.
		Operation enabled	[52]	TRUE if inverter and start are enabled. Otherwise FALSE.
		Stop active	[53]	TRUE if inverter is enabled and motor is not started and output frequency = 0.
		Error active	[56]	TRUE if error is active. Otherwise FALSE.
		Device warning active	[58]	TRUE if warning is active. Otherwise FALSE.
P420.02	DO1 function	Release brake	[115]	Assignment of a trigger to digital output 1. Trigger = FALSE: X3/DO1 set to LOW level. Trigger = TRUE: X3/DO1 set to HIGH level.
P430.01	AI1 input area	0 ... 10 VDC	[0]	Definition of the input range for analog input AI1.
		0 ... 5 VDC	[1]	
		2 ... 10 VDC	[2]	
		-10 ... +10 VDC	[3]	
		4 ... 20 mA	[4]	
		0 ... 20 mA	[5]	
P430.02	AI1 freq @ min	-1000.0 ... 0.0 ... 1000.0 Hz		Scaling of the input signal AI1 to the frequency value.
P430.03	AI1 freq @ max	-1000.0 ... 50.0 60.0 ... 1000.0 Hz *		<ul style="list-style-type: none"> • Direction of rotation according to sign. • The standard setpoint source for operating mode "MS: Velocity mode" is selected in P201.01.
P440.01	AO1 output area	Disabled	[0]	Definition of the output range for analog output AO1.
		0 ... 10 VDC	[1]	
		0 ... 5 VDC	[2]	
		2 ... 10 VDC	[3]	
		4 ... 20 mA	[4]	
		0 ... 20 mA	[5]	

* Default setting dependent on the model



Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

Favorites (group 0)










Display-Code	Name	Possible settings/ Value ranges	Keypad code	Information
P440.02	AO1 function	Output frequency	[1]	Actual output frequency (resolution: 0.1 Hz).
		Frequency setpoint	[2]	Actual frequency setpoint (resolution: 0.1 Hz).
		Analog input 1	[3]	Input signal of analog input 1 (resolution: 0.1 %).
P440.03	AO1 Min. Signal	-2147483648 ... 0 ... 2147483647		Definition of the signal value that corresponds to the minimum value at analog output 1.
P440.04	AO1 Max. signal	-2147483648 ... 1000 ... 2147483647		Definition of the signal value that corresponds to the maximum value at analog output 1.
P450.01	Freq. preset 1	0.0 ... 20.0 ... 599.0 Hz		Parameterizable frequency setpoints (preset 1).
P450.02	Freq. preset 2	0.0 ... 40.0 ... 599.0 Hz		Parameterizable frequency setpoints (preset 2).
P450.03	Freq. preset 3	0.0 ... 50.0 60.0 ... 599.0 Hz *		Parameterizable frequency setpoints (preset 3).
P450.04	Freq. preset 4	0.0 ... 0.0 ... 599.0 Hz		Parameterizable frequency setpoints (preset 4).

* Default setting dependent on the model



Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions




















Basic setting (group 2)

Display-Code	Name	Possible settings	Keypad code	Information
P225.00	QSP del.time	1.0 s		Quick stop deceleration time for "MS: Velocity mode" <ul style="list-style-type: none"> If the "Quick stop" function is activated, the motor is brought to a standstill within the deceleration time set here. The braking deceleration time set refers to the deceleration from the maximum frequency set (P211.00) to standstill. In the case of a lower actual frequency, the actual deceleration time is reduced accordingly. Setting is not effective in the operating mode P301.00 = "CiA: Velocity mode [2]".

Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control**
- Additional functions




















Motor control (group 3)

Display-Code	Name	Possible settings	Keypad code	Information	
P320.04	Rated torque	50 ... 50000 rpm		General motor data. Carry out settings as specified by motor nameplate data. Note! When you enter the motor nameplate data, take into account the phase connection implemented for the motor (star or delta connection). Only enter the data applying to the connection type selected.	
P320.05	Rated frequency	1.0 ... 10000.0 Hz			
P320.06	Rated power	0.00 ... 655.35 kW 0.00 ... 878.84 hp			
P320.07	Rated voltage	0 ... 65535 V			
P320.08	Cos phi	0.00 ... 1.00			
P327.04	Mot. identif.	0 ... 1			1 = start automatic identification of the motor data. • Inverter characteristics, motor equivalent circuit diagram data and controller settings are identified and set automatically. • During the procedure, the motor is energized!
P327.05	Mot. calibrate	0 ... 1			1 = start automatic calibration of the motor data. • A default inverter characteristic is loaded. • The motor equivalent circuit diagram data and controller settings are calculated on the basis of the currently set rated motor data. • The motor is not energized.

Commissioning

- Initial switch-on
 - Important notes
 - Keypad module
 - Keypad control
 - Terminal control
 - Extended terminal control
 - Parameter overview
 - Favorites
 - Basic setting
 - Motor control
- Additional functions

Additional functions (group 7)

Display-Code	Name	Possible settings	Keypad code	Information
P700.01	Load default settings	On / start	[1]	1 = reset all parameters in the RAM memory of the inverter to the default setting stored in the inverter firmware. • All parameter changes made by the user are lost during this process! • This process may take some seconds. When the device command has been executed successfully, the value 0 is shown. • Loading parameters has a direct effect on cyclic communication: The data exchange for control is interrupted and a communication error is generated.
		Off/ready	[0]	Only status feedback
P700.03	Save user data	On / start	[1]	1 = save current parameter settings in the user memory of the memory module with mains failure protection. • This process may take some seconds. When the device command has been executed successfully, the value 0 is shown. • Do not switch off the supply voltage during the saving process and do not unplug the memory module from the inverter! • When the inverter is switched on, all parameters are automatically loaded from the user memory of the memory module to the RAM memory of the inverter.
		Off/ready	[0]	Only status feedback

Troubleshooting

Error message

Error codes

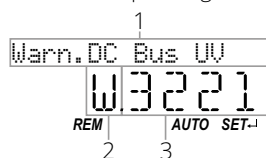
LED status

Support



Error message

If an error is pending, the keypad shows the following information.



1 = Error text

2 = Error type (F = fault, T = trouble, W = warning)

3 = Error code (hexadecimal)

- Faults (F) and trouble (T) are displayed continuously. The inverter is disabled.
- Warnings (W) are displayed every 2 seconds for a short time. The inverter is probably disabled.

Reset error via keypad

Errors can be reset via the stop key.

- Prerequisite: Cause of error has been eliminated and no blocking time is active.
- Press the stop key to reset the error. The motor is stopped.
- Press the start key to cancel the stop.

Reset error via terminal control

When terminal control is used, errors can be reset in two ways:

1. Via start signal P400.02 (default setting of digital input 1).
 - Prerequisite: Cause of error has been eliminated and no blocking time is active.
 - The signal at the digital input 1 must drop and then be applied again.
2. Via error reset signal (P400.04, default setting of digital input 2).
 - Prerequisite: Cause of error has been eliminated and no blocking time is active.
 - The error is reset if a signal is applied to digital input 2.

Troubleshooting

Error message

Error codes

LED status

Support



Error codes

Error code	Description	Classification	Remedy	Blocking time [s]
2250	CiA: Continuous overcurrent (inside the device)	Error	<ul style="list-style-type: none"> • Check motor and wiring for short circuits. • Check brake resistor and wiring. • Check motor circuit (delta connection, star connection). • Check setting of the motor data. 	5
2320	Short circuit or earth leakage on the motor side	Error	<ul style="list-style-type: none"> • Check motor cable. • Check the length of the motor cable. • Use shorter or lower-capacitance motor cable. 	5
2340	CiA: Short circuit (inside the device)	Error	<ul style="list-style-type: none"> • Check motor cable for short circuit. 	5
2350	CiA: i ² *t overload (thermal state)	Error	<ul style="list-style-type: none"> • Check drive dimensions. • Check machine/driven mechanics for excessive load. • Check setting of the motor data. • Reduce values for slip compensation (P315.01, P315.02) and oscillation damping (P318.01, P318.02). 	5
2382	Error: Device utilization (Ixt) too high	Error	<ul style="list-style-type: none"> • Check drive dimensions. • Reduce maximum overload current of the inverter (P324.00). • In case of high mass inertias, reduce maximum overload current of the inverter (P324.00) to 150 %. 	3
2383	Warning: Device utilization (Ixt) too high	Warning	<ul style="list-style-type: none"> • Check drive dimensions. 	0
3120	Mains phase fault	Error	<ul style="list-style-type: none"> • Check mains connection wiring. • Check fuses. 	0
3210	DC bus overvoltage	Error	<ul style="list-style-type: none"> • Reduce dynamic performance of the load profile. • Check mains voltage. • Check settings for the braking energy management. 	0
3211	Warning: DC bus overvoltage	Warning	<ul style="list-style-type: none"> • Connect brake resistor to the power unit and activate the integrated brake chopper. (P706.01 = 0: Brake resistance) 	0
3220	DC bus undervoltage	Trouble	<ul style="list-style-type: none"> • Check mains voltage. • Check fuses. 	0
3221	Warning: DC bus undervoltage	Warning	<ul style="list-style-type: none"> • Check DC bus voltage (P105.00). • Check mains settings. 	0
3222	DC-bus voltage too low for switch-on	Warning	<ul style="list-style-type: none"> • Check mains voltage. • Check fuses. • Check mains settings. 	0
4210	PU: Overtemperature fault	Error	<ul style="list-style-type: none"> • Check mains voltage. • Provide for a sufficient cooling of the device (display of the heatsink temperature in P117.01). • Clean fan and ventilation slots. If required, replace fan. • Reduce switching frequency (P305.00). 	0
4281	Heatsink fan warning	Warning	<ul style="list-style-type: none"> • Clean fan and ventilation slots. If required, replace fan. The fans can be unlocked via locking hooks and can then be removed. 	0
4310	Error: Motor overtemperature	Error	<ul style="list-style-type: none"> • Check drive dimensions. • Check motor thermal sensor and wiring (terminals X109/T1 and X109/T2). 	5
5112	24 V supply critical	Warning	<ul style="list-style-type: none"> • Check optional external 24 V voltage supply (terminal X3/24E), if connected. • Check mains voltage. 	0
5180	24-V supply overload	Warning	<ul style="list-style-type: none"> • Check 24 V output and digital outputs for earth fault or overload. 	0



Troubleshooting

Error message

Error codes

LED status

Support



Error codes

Error code	Description	Classification	Remedy	Blocking time [s]
6280	Trigger/functions connected incorrectly	Trouble	<ul style="list-style-type: none"> Check and correct the assignment of the triggers to the functions. With keypad or network control, the two functions "Inverter enable" (P400.01) and "Run" (P400.02) can also be set to "Constant TRUE [1]" to start the motor. 	0
7180	Motor overcurrent	Error	<ul style="list-style-type: none"> Check motor load. Check drive dimensions. Adapt the set error threshold (P353.01). 	1
9080	Keypad removed	Error	<ul style="list-style-type: none"> Connect the keypad again or activate another control source. 	0
FF02	Error: Brake resistor overload	Error	<ul style="list-style-type: none"> Check drive dimensions. Check settings for the braking energy management. Note! The error will be reset if the thermal load falls below the error threshold (P707.09) - 20 %. 	5
FF06	Motor overspeed	Error	<ul style="list-style-type: none"> Adapt the maximum motor speed (P322.00) and the error threshold (P350.01). 	1
FF36	Warning: Brake resistor overload	Warning	<ul style="list-style-type: none"> Check drive dimensions. Check settings for the braking energy management. Note! The warning will be reset if the thermal load falls below the warning threshold (P707.08) - 20 %. 	0
FF37	Automatic start disabled	Error	<ul style="list-style-type: none"> Deactivate start command and reset error. 	0
FF85	Keypad full control active	Warning	<ul style="list-style-type: none"> Press the CTRL key to exit control mode. 	0



Troubleshooting

- Error message
- Error codes
- LED status
- Support

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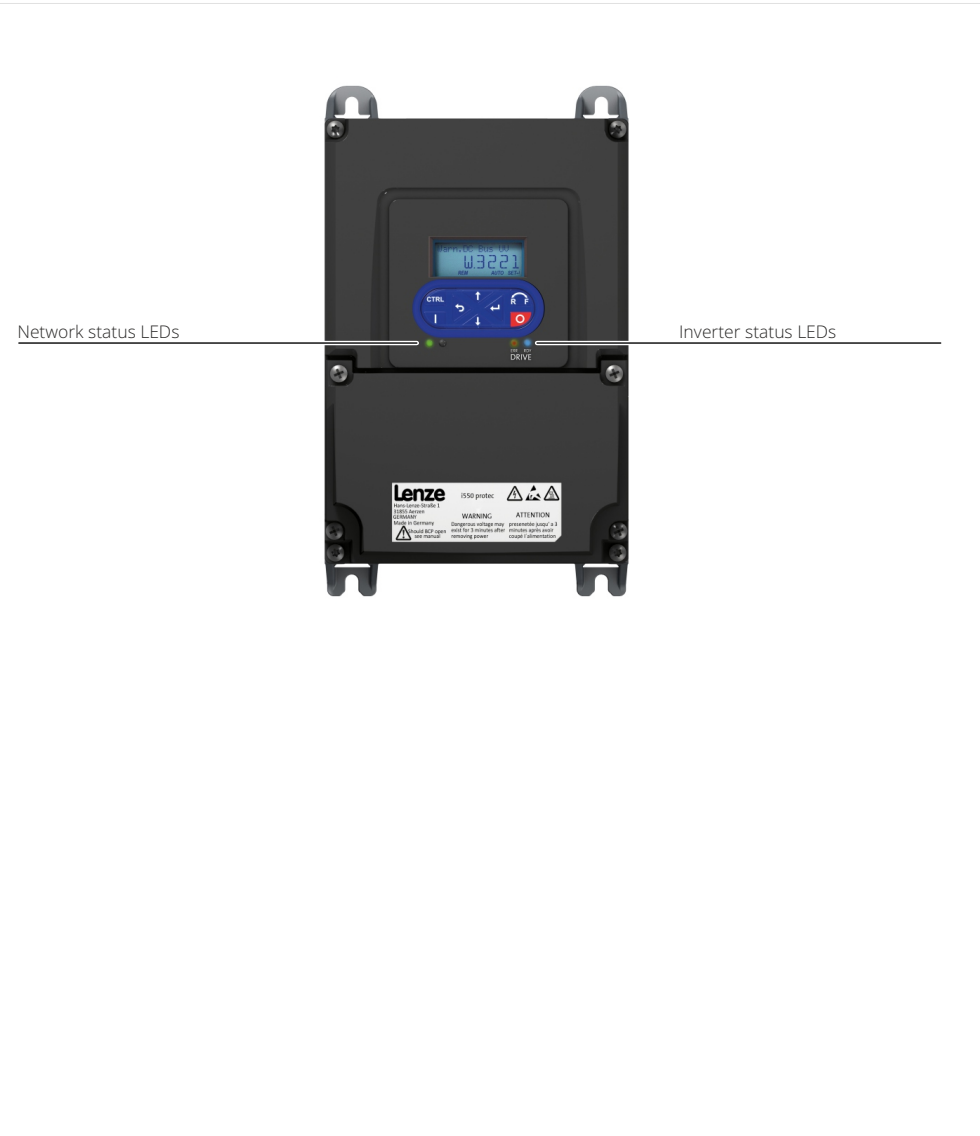
LED status

Meaning of the status LEDs for the inverter:

LED "RDY" (blue)	LED "ERR" (red)	State/meaning
off	off	No supply voltage
		Mains voltage is switched on, inverter initialized
	off	Inverter disabled, ready for operation
blinking		Safe torque off (STO) active, warning active
	off	Inverter disabled
		Inverter disabled, warning active.
blinking		Inverter disabled, error active.
		Inverter disabled, no DC bus voltage.
	off	Enable inverter
	off	The motor rotates according to the specified setpoint or quick stop active.
		Inverter enabled, warning active. The motor rotates according to the specified setpoint or quick stop active.
		Inverter enabled, quick stop active as response to a fault.

Meaning of the status LEDs for the different networks:

Network	Left LED (green)	Right LED (red)
CANopen	CAN RUN	CAN-ERR
EtherCAT	RUN	ERR
EtherNet/IP	NS	ms
Modbus RTU	COMM	ERR
Modbus TCP	NS	ms
PROFINET	BUS-RDY	BUS-ERR
IO-Link	RUN	-



Troubleshooting

Error message

Error codes

LED status

Support



Support

Further information can be found on the online page


www.lenze.com/product-information



The material number of the product can be found on the nameplate.



Disposal

	<p>If pollutants are disposed off improperly, they may cause a lasting damage to human health and the environment. Thus, electrical and electronic equipment must be collected separately from unsorted municipal waste so that it may be recycled or disposed of properly. If available, put the components to the company internal disposal from where it is passed on to specialized waste management companies. It is also possible to return the components to the manufacturer. For this purpose, please contact the customer service of the manufacturer. More detailed information on disposal can be obtained from the corresponding specialist firms and the competent authorities. The packaging of the component must be disposed of separately. Paper, cardboard and plastics must be recycled.</p>
